

## Worksheet 1 Solutions

$$(1) \quad x(t) = A l + A \cos(\omega t)$$

$$x(t) = 20 + 5 \cos(\omega t)$$

$$\min(x(t)) = 20 + 5 \cos(\pi)$$

$$= 20 - 5$$

$$= 15 \text{ [cm]}$$

$$(2) \quad x(t) = A \cos(\omega t)$$

$$= 0.07 \cos(2\pi t)$$

$$\omega = 2\pi f$$

$$v(t) = -2\pi \cdot 0.07 \sin(2\pi t)$$

$$t = \frac{1}{4} \text{ When passes through}$$

$$= -2\pi \cdot 0.07 \sin\left(\frac{\pi}{2}\right)$$

$$= -2\pi \cdot 0.07$$

$$\|v(t)\| = 0.44 \text{ [m]}$$

$$(3) \quad v = \frac{\text{circumference}}{\text{Period}} = \frac{2\pi r}{T} = 2\pi r \cdot f = r\omega$$

$$\omega = \frac{v}{r} = \frac{343}{3} = 114.3 \text{ [rad/s]}$$

$$(4) \quad x(t) = A \cos(\omega t) e^{-\lambda t} \hat{x}$$

$$v(t) = \left[ -A\omega \sin(\omega t) e^{-\lambda t} - A\lambda \cos(\omega t) e^{-\lambda t} \right] \hat{x}$$

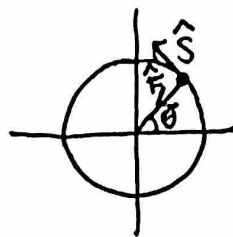
$$= -A e^{-\lambda t} [\lambda \cos(\omega t) + \omega \sin(\omega t)] \hat{x}$$

$$(5) \quad v(t) = A \cos(\omega t) e^{-\lambda t} \hat{x}$$

$$k = \frac{m v^2}{2}$$

$$K(t) = \frac{m A^2 \cos^2(\omega t) e^{-2\lambda t}}{2}$$

(6)  $\vec{a} = -\frac{v^2}{|r|} \hat{r}$ ,  $F = ma$



$$W = \int_S ds \cdot F = \int_0^{2\pi} d\theta F \cos\left(\frac{\pi}{2}\right)$$

← angle between  $\vec{F}$  and  $\hat{S}$   
 $A \cdot B = AB \cos(\theta)$

$$= \int_0^{2\pi} d\theta \cdot 0$$

$= 0$  hence motion is "uniform" circular

(7)  $f = \frac{90}{60} = 1.5 \rightarrow \omega = 2\pi f = 3\pi$

$$\omega = \sqrt{\frac{mgd}{I}} \Rightarrow d = \frac{I\omega^2}{mg} = \frac{2.07 \cdot (3\pi)^2}{12 \cdot 9.8} = 1.56 \text{ [m]}$$

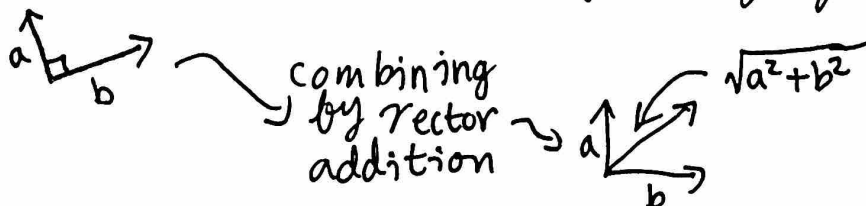
this shows the leg is not a S.H.O.

(8)(9)  $T = 2\pi \sqrt{\frac{I}{g}} \rightarrow m, \theta$  are irrelevant (unless  $\theta = 0$ )!

if  $g = \pi^2 \rightarrow T = 2\sqrt{l} \rightarrow$  one second period

$\rightarrow l = \frac{1}{4} = 0.25 \text{ [m]}$

(10) Visualize as phasors: (rotate the axis at  $\omega$  angular frequency, while keeping the angle fixed)



(11)  $x(t) = A \cos(\omega t + \phi)$   
 $v(t) = -A\omega \sin(\omega t + \phi)$

bounded by  $[-1, 1] \rightarrow$  max  $v(t) = A\omega$

$$(12) \quad k = \frac{m\gamma^2}{2} = \frac{m^2\gamma^2}{2m} = \frac{p^2}{2m}$$

$$(13) \quad e^{i\theta} = \cos(\theta) + i\sin(\theta) \rightarrow \begin{aligned} \cos(\theta) &= \frac{e^{i\theta} + e^{-i\theta}}{2} \\ \sin(\theta) &= \frac{e^{i\theta} - e^{-i\theta}}{2i} \end{aligned}$$

$$\begin{aligned} 2 \sin(ax) \cos(ax) &= 2 \left[ \frac{e^{iax} - e^{-iax}}{2i} \right] \left[ \frac{e^{iax} + e^{-iax}}{2} \right] \\ &= \frac{1}{2i} \left[ e^{2iax} + 1 - 1 - e^{-2iax} \right] \\ &= \sin(2ax) \end{aligned}$$

(14) This is not a very good question because  $\vec{\omega}$  is a non-linear function of time

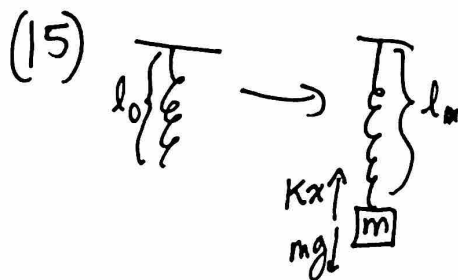
What it was going for was at the mean  $\omega$ , what would this be,

which works out as  $\omega = \frac{25}{60} \cdot 2\pi = 8.90$ ,  $I = \frac{m l^2}{3} = 3.54$



$$k = \frac{\omega \cdot I \times \omega}{2} = \frac{I \omega^2 \cos(0) \sin \frac{\pi}{2}}{2}$$

$$= \frac{I \omega^2}{2} = \frac{140.9 \text{ [J]}}{2}$$



$$\Delta x \equiv l - l_0 \leftarrow \text{defn.}$$

$$mg = kx \leftarrow \text{at rest}$$

$$\Delta x = \frac{mg}{k} = \frac{0.2 \cdot 9.8}{5} = 0.392 \text{ [m]}$$

$$x(t) = l - \Delta x \cos(\omega t + \phi) \quad \leftarrow \begin{matrix} \sqrt{\frac{m}{k}} \\ \phi \text{ here} \end{matrix}$$

$$= 0.1 + 0.392 - 0.392 \cos(5t)$$

$$= 0.492 - 0.392 \cos(5t)$$

(16) This problem is not solvable using analytic techniques. Alas.

(17) See message in the groupme.

(18) If  $\omega_d \rightarrow \omega$ , then  $\omega_d = \sqrt{\frac{k}{m}}$ , so  $A = \frac{\|F_d\|}{\sqrt{b^2 k/m}}$

If  $b \rightarrow 0$  as well, then  $A \rightarrow \infty$

Bad things happen if  $A \rightarrow \infty$ . We want to avoid this.

(19)  $\omega_d = \frac{120}{60} \cdot 2\pi = 4\pi$

$$F_d = mg = 40 \cdot 60 \cdot 10 = 2400 \text{ [N]}$$

$$A = \frac{2400}{\sqrt{(10^6 - 10^5 \cdot (4\pi)^2)^2 + (4\pi \cdot 10^4)^2}} = 0.000162 \text{ [m]}$$

So this bridge is well designed to handle this load.